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Andrea Maggiolo-Schettini and
Józef Winkowski
A FORMALISM
FOR PROGRAMMED REWRITING OF (HYPER)GRAPHS*

745

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INSTITUTE OF COMPUTER SCIENCE POLISH ACADEMY OF SCIENCES


# Andrea Maggiolo-Schettini and <br> Józef Winkowski <br> A FORMALISM FOR PROGRAMMED REWRITING OF (HYPER )GRAPHS* 

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## Abstract. Streszczenie

The paper presents a formalism for rewriting (hyper)graphs in a controlled manner. This formalism is essentially a simple programming language with productions, that is rewriting rules, playing the role of basic instructions. The programs in this language are built from productions by means of rather standard constructors, including a parallel composition. They may contain parameters to point to specific elements of graphs to which they are supposed to be applied. The programs are intended to describe how to transform a graph and a valuation of parameters in this graph in order to reach a resulting graph and a resulting valuation of parameters.

## FORMALIZM DO PROGRAMOWANLA TRANSFORMACJI (HYPER)GRAFÓW

Praca prezentuje formalizm do kontrolowanego przetwarzania (hyper)grafów. Formalizm ten stanowi $w$ istocie prosty jegzk programowania 2 produkcjami, tzn. regulami przetwarzania, odgrywającymi roleg instrukcji podstawowych. Programy w tym jȩzyku są budowane 2 produkcji za pomoç typowych konstruktonów programotwórczych wśród których jest zlơ̇enie równolegle. Programy moga zawierać parametry. Parametry programu wskazuj̧̧ elementy grafów do których ten program ma być stosowany. Ogólnie, program opisuje jak transformować grafi wartościowanie parametrów w tym grafie ażeby uzyskać graf wynikowy j wynikowe wartościowanie parametrów.

## Key words:

(hyper)graph, rewriting rule, production, parametrized production, rewriting step, program of rewriting, structured operational semantics, resulting relation.

## 1 Introduction

Some models of computing can be formulated in a natural manner in terms of rewriting of appropriate data structures represented as graphs. Take, for instance, the representation of actor systems as in [JaRo 91] or that of logic programs in [CMREL 91].

A theory of graph rewriting systems bas been developed which describes how to rewrite graphs according to formal rules called productions, where a rule says that a certain given pattera can be replaced by another pattern if it occurs in a graph, and where graphs may be of very general types, including hypergraphs, coloured hypergraphs, relational structures, etc. (cf. [CER 79], [EKMRW 82], [ENR 83], (ENRR 87], [EKR 91]). This theory in its pure form does not assume anything about where and in what order to apply productions. In this situation at each stage of rewriting an independent search of an applicable rule and of a place of application must be done, which in general is a task of high complexity. On the other hand, in some problems the structure of data and the algorithm to solve the problem allow to organize rewriting in an efficient manner.

This paper presents a formalism with mechanisms which make such an organized rewriting possible. Our formalism is in the framework of the algebraic approach proposed in [EPS 73]. It is essentially a kernel of a simple programming language with productions playing the role of basic instructions. Programs are built in this formalism from productions by means of rather standard constructors which define the order and modalities of rewriting steps. Among the program constructors there is a parallel composition which declares the possibility of executing programs in parallel. The parallelism is understood here as an arbitrary interleaving of atomic (i.e. indivisible) actions of component programs, where atomic actions are either single instructions or complexes of instructions which are specified as atomic with the aid of a special constructor. Productions and programs may contain parameters to point to particular elements of graphs to which they are supposed to be applied. When applied to pairs consisting of a graph and a valuation of parameters in this graph they transform such pairs one into another as long as it follows from their meaning. The mechanism of accessing graphs through valuations of parameters allows to enforce components of a program to operate on the same data and to realize shared variables whose values represent some parts of data.

The presented formalism is endowed with a structured operational semantics in the style of [Plo 81]. This semantics defines the possible executions of a program. Conse-
quently, it determines the corresponding relations between the data and results of performed executions.

The formalism we define may be useful whenever a problem can naturally be reduced to graph rewriting and the process of rewriting is too complex to be represented as a result of a free application of a system of productions. We shall illustrate it on example of a concurrent execution of a program in a simple concurrent logic language (called FCP after [Sh 89]).
1.1. Example. Consider the logic program:

```
\(\operatorname{sum}(Y, S) \leftarrow \operatorname{sum}^{\prime}(Y, 0, S)\)
\(\operatorname{sum}^{\prime}(0, P, S) \leftarrow P=S\)
\(\operatorname{sum}^{\prime}([X \mid Y], P, S) \leftarrow p l u s(X, P, Q), \operatorname{sum}^{\prime}(Y, Q, S)\)
plus \((0,0, X) \leftarrow X=0\)
plus \((0,1, X) \leftarrow X=1\)
```

When applied to the goal sum $([1,2], S)$ this program computes the sum of elennents of the list $Y=[1,2]$ and assigns the result to $S$.

If such a program is regarded as a concurrent logic program in FCP then the atomic formula of the goal and those which are obtained by applying the clauses of this program to the goal can be viewed as processes which communicate via their variables (in [ Sb 89] such variables are called logical ones). Each process of this type keeps trying to match its formula (that is the formula it corresponds to) with a clause head by a suitable substitution of terms for variables, and, if successful, it creates processes corresponding to the atomic formulas of the right hand side of the clause. This procedure may imply an instantiation of variables the process shares with other existing processes. Due to this, the processes awaiting for such an instantiation may advance.

For our program and goal we obtain the following computation:

```
sum \(([1,2], S)\)
sum \(^{\prime}([1,2], 0, S)\)
plus(1,0,P), sumí([2], \(P, S)\)
plus \((1,0, P)\), plus \((2, P, Q)\), sum \((\square, Q, S)\)
\(P=1\), plus \((2, P, Q)\), sum \(^{\prime}(\square, Q, S)\)
\(P=1\), plus \((2, P, Q), Q=S\)
\(P=1\), plus \((2, P, S)\)
plus(2,1,S)
\(S=3\).
```

In this computation $S, P, Q$ are variables. In order to find the required sum and assign it to $S$, the process sum $([1,2], S)$ matches its formula with the head of the first clause and creates the process sum" $([1,2], 0, S)$. This process matches its formula with the third
clause and creates two parallel processes plus $(1,0, P)$ and $\operatorname{sum}^{\prime}([2], P, S)$ which contain a new variable $P$. Now plus $(1,0, P)$ instantiates $P$ to 1 and $s^{\prime}([2], P, S)$ evolves into plus $(2, P, Q)$ and $\operatorname{sum}^{\prime}([1, Q, S)$. The processes plus $(1,0, P)$ and plus $(2, P, Q)$ synchronize in the sense that plus $(2, P, Q)$ waits for instantiation of $P$ to 1 in order to instantiate $Q$. As simultancously $S$ is instantiated to $Q$ duc to the second clause, we obtain finally the required result $S=3$.

In our approach each state of a computation of this type is represented by a jungle as in [CR 93]. For instance, the state plus $(1,0, P), s u m^{\prime}([2], P, S)$ is represented as shown in figure 1.1. In this representation hyperedges correspond to concrete occurrences of predicate and function symbols and nodes represent terms (more precisely, nodes are roots of subjungles which represent terms). For instance, the node $\sigma$ represents the term 210 , that is the list [2].


Figure 1.1

Processes which take part in a computation are present in it as subjungles which represent the respective atomic formulas. They are realized by calling with suitable values of parameters and executing, possibly many times, programs which specify how a process of a given class performs its step. Such a realization leads usually to parallel processes and then it appears as an interleaving of actions of the existing processes which is synchronized solely by instantiations of variables shared by processes.

For an illustration of this way of representing and realizing of processes let us consider the process plus $(1,0, P)$. Each step of this process can be realized by calling with $\xi$ representing 1 and $\eta$ representing 0 , and with $\zeta=P$, and executing a program $P L U S(\xi, \eta, \zeta)$ whose body can be defined as

$$
\begin{aligned}
& \Sigma x \Sigma y \quad \text { if } \xi \text { represents } x \text { and } \eta \text { represents } y \\
& \text { then replace plus }(\xi, \eta, \zeta) \text { by } \zeta=x+y \\
& \text { else } \operatorname{PLUS}(\xi, \eta, \zeta)
\end{aligned}
$$

where replace plus $(\xi, \eta, \zeta)$ by $\zeta=x+y$ denotes a reduction of the jungle which represents
plus $(\xi, \eta, \zeta)$ (see the leftmost jungle in figure 2.4) to a single edge without target nodes, with a single source node $\zeta$, and with the colour equal to the sum of $x$ and $y$ (see the rightmost jungle in figure 2.4), and where $\Sigma x$ and $\Sigma y$ denote an indeterministic choice of some instances of $x$ and $y$ in the jungle to which the program is applied. Each call of $P L U S(\xi, \eta, \zeta)$ is an attempt of instantiating variables of terms represented by $\xi, \eta, \zeta$. If successful, it terminates the process plus $(1,0, P)$ with $P=x+y$. Otherwise it causes a subsequent call of $\operatorname{PLUS}(\xi, \eta, \zeta)$ which may be viewed as a subscquent step the process plus $(1,0, P)$ to be realized (possibly in parallel with other processes) after completing the current step.

Similarly, each step of the process $3 u m^{\prime}([1,2], 0, S)$ can be realized by calling with $\xi$ representing $[1,2], \eta$ representing 0 , and with $\zeta=S$, and exccuting a program $S U M M^{\prime}(\xi, \eta, \zeta)$ whose body can be defined as

```
\SigmaX\SigmaY if \xirepresents [X|Y]
    then \Sigma\varrho (replace sum'}(\xi,\eta,\zeta) by plus(X,\eta,\varrho) and sum'(Y,\varrho,\zeta);
    (PLUS(X,\eta,\varrho)|| SUM'(Y,\varrho,\zeta)))
else if \xirepresents []
    then replace sum'(}},\eta,\zeta) by \zeta=
    else SUM'(\xi,\eta,\zeta))
```

where ( $P L U S(X, \eta, \varrho) \| S U M^{\prime}(Y, \varrho, \zeta)$ denotes the parallel interleaving execution of programs $P L U S(X, \eta, \varrho)$ and $S U M^{\prime}(Y, \varrho, \zeta)$, and

$$
\begin{aligned}
& \text { replace sum }(\xi, \eta, \zeta) \text { by plus }(X, \eta, \varrho) \text { and } \operatorname{sum}^{\prime}(Y, \varrho, \zeta) \text {, } \\
& \text { replace } \operatorname{sum}^{\prime}(\zeta, \eta, \zeta) \text { by } \zeta=0
\end{aligned}
$$

are the operations of replacing the leftmost jungle by the rithtmost one in figures 2.2 and 2.4 , respectively. The call of $S U M^{\prime}(\xi, \eta, \zeta)$ if $\xi$ represents the cmpty list [] may be viewed as a subsequent step of the realized process $3 u m^{\prime}([1,2], 0, S)$ whereas $P L U S(X, \eta, \varrho)$ and $S U M^{\prime}(Y, \varrho, \zeta)$ start two new processes plus $(1,0, P)$ and $s u m^{\prime}([2], P, S)$.

The present paper extends and improves a previous work in [MW 83], [MW 91], and [MW 92]. It is organized as follows. In section 2 we recall and modify for our purposes the basic notions related to rewriting graphs. In section 3 we define programs of rewriting graphs. In section 4 we present a structured operational semantics of these programs. In section 5 we describe input-output relations of programs.

## 2 Graphs, productions, and derivations

Let $\Lambda$ be a fixed many-sorted first-order language with equality which has sorts nodes, edges, colours, operation symbols
none : $\rightarrow$ nodes,
1 source, ..., m.source, l_target, ..., nlarget: edges $\rightarrow$ nodes, edgecolour: edges $\rightarrow$ colours,
$\omega_{1}:$ colours $\times \ldots \times$ colours $\rightarrow$ colours, $\omega_{2}:$ colours $\times \ldots \times$ colours $\rightarrow$ colours, etc., and infinite, mutually disjoint sets nodevariables, edgevariables, colourvariables of node, edge, and colour variables, respectively.

Let $\Omega$ denote the signature consisting of the sorts and operation symbols of $\Lambda$ and $\Omega_{0}$ the part of $\Omega$ consisting of the sort colours and operation symbols $\omega_{1}, \ldots$.

By an $\Omega$-graph (or a graph) we mean an $\Omega$-algebra $G$ such that i_sourceg $(x)=$ noneg
 noneG for $j \geq i$. By source $(x)$ (resp.: by $\left.\operatorname{target}_{G}(x)\right)$ we denote the string of subsequent different from nonec nodes isource ${ }_{C}(x)$ (resp.: the string of subsequent different from noneg nodes $i_{\text {farget }}^{G}(x)$ ). Thus we obtain functions
source $_{G}$, target $_{G}:$ edges $_{G} \rightarrow\left(\text { nodes }_{G}\right)^{-}$.
By an $\Omega$-homomorphism from an $\Omega$-graph $G$ to an $\Omega$-graph $G^{\prime}$ we mean any homomorphism $h: G \rightarrow G^{\prime}$ from the $\Omega$-algebra $G$ to the $\Omega$-algebra $G^{\prime}$, and by $h_{\text {nodeo, }} h_{\text {dede.e. }}$, $h_{\text {colours, }}$, we denote the components of $h$ corresponding to the sorts nodes, edges, colours, respectively.

By $\Omega$-graphs we denote the category of $\Omega$-graphs and $\Omega$-homomorphisms.
The category $\Omega$-graphs enjoys the following property.
2.1. Proposition. Each pair of $\Omega$-homomorphisms of the form $(L \backsim K \leftrightarrows D)$ such that the pair ( $\Omega_{0}$ reduct $(L)^{t_{\text {eplow }}} \Omega_{0}$ reduct $(K) \stackrel{\text { dawn }}{ } \Omega_{0}$ reduct $(D)$ ) has a pushout ( $\Omega_{0}$ _reduct $(L){ }^{\prime} \rightarrow X \Omega_{0}$ reduct $(D)$ ) in the category of $\Omega$-algebras has also a pushout $(L \xrightarrow{\&} G \leftarrow D)$ in $\Omega_{\text {graphs, }}$ where $\Omega_{0}$ reduct $(G)=X, g_{\text {colour, }}=g^{\prime}, b_{\text {colour, }}=b^{\prime}$, nodesg, edgesG, $g_{\text {nodeo }} g_{\text {edges }}, b_{\text {nodes }}, b_{\text {elges }}$ are obtained from the respective pushouts in the category of sets, and isourceg, ifarget , edgecolourc are determined by the properties of $\Omega$-graphs.

In particular, if we are not interested in operations on colours, and so in $\Omega$ there are as operation symbols, then ( $\Omega_{0}$ reduct $(L)$ "err $\Omega_{0} \operatorname{reduct}(K)$ dent $\Omega_{0}$ reduct $(D)$ ) is a diagram in the category of sets. Consequently, the corresponding category $\Omega$.graphs has pushouts.

The fact that nodesg, edgesg, $g_{\text {nodes }} g_{\text {cdgeo }}, b_{\text {noder }}, b_{\text {edjee }}$ can be taken from the respective pushouts in the category of sets is straightforward.

As far as the definitions and uniqueness of isource , isarget $_{G}$, edgecolourg are concerned, they follow from the fact that, if an edge $x \in$ edges ${ }_{L}$ has isource $_{L}(x)=y$, $j$ farget $L_{L}(x)=z$, and edgecolour $L(x)=u$, then the only candidate for i.sourcec $\left(g_{\text {rdgee }}(x)\right)$ is $g_{\text {nodec }}(y)$, the only candidate for $j$ target $\sigma\left(g_{\text {cdgeo }}(x)\right)$ is $g_{\text {nodee }}(z)$, and the only candidate for edgecolourg $\left(g_{\text {rdges }}(x)\right)$ is $g_{\text {coloure }}(u)$.

In this paper we restrict ourselves to special pushouts.
Given a pair of $\Omega$-homomorphisms $(L \stackrel{\llcorner }{\leftarrow} K \stackrel{4}{\rightarrow} D$ ) and a pushout $(L \stackrel{Q}{\leftrightarrows} G \stackrel{b}{\leftrightarrows} D$ ) of this pair, we call this pushout natural, and we call $(K \stackrel{d}{\rightarrow} D \xrightarrow{b} G)$ the natural pushout complement of $(K \stackrel{t}{\rightarrow} L \stackrel{\Xi}{\longrightarrow}$ ), if the components of $b: D \rightarrow G$ are inclusions.

For our purposes we shall have to do only with cases in which natural pushouts and pushout complements can be obtained in a particularly simple way.

Let $\Omega_{0}$-ierms be the $\Omega_{0}$-algebra of terms with colour variables. From the universal property of free algebras we obtain the following proposition.
2.2. Proposition. For each $\Omega_{0}$-algebra $A$ and each $\Omega_{0}$-homomorphism a: $\Omega_{0}$ terms $\rightarrow$ A, the diagram ( $\Omega_{0}$-lerms $\stackrel{i d e n t i t y}{\leftrightarrows} \Omega_{0}$-ierms) $\rightarrow$ A) has a pushout and the diagram ( $\Omega_{0}$ ferms $\xrightarrow{a} A \stackrel{\text { iLentity }}{\longleftarrow} A$ ) is such a pushout.

From this proposition we obtain immediately the following one.
2.3. Proposition. Each pair of morphisms ( $L \stackrel{t}{\leftarrow} \xrightarrow{d} D$ ) with $\Omega_{0}$ reduct $(L)$ and $\Omega_{0} \operatorname{reduct}(K)$ equal to $\Omega_{0}$ terms, and with $K^{l_{\text {ceters }}} L$ being the identity homomorphism, has a natural pushout $(L \stackrel{\leftrightarrow}{\rightarrow} G \stackrel{\llcorner }{\leftarrow} D$.
2.4. Proposition. Each pair of $\Omega$-homomorphisms $\left(K \xrightarrow{1} L \xrightarrow{?} G\right.$ ) such that $\Omega_{0}$ reduct $(L)$ and $\Omega_{0} \operatorname{reduct}(K)$ are equal to $\Omega_{0}$ _herms, $K^{\text {ledenf }^{\prime}} L$ is the identity homomorphism, $g_{\text {node, }}$ is one-to-one in nodes $L_{L}-l_{\text {nodes }}\left(\right.$ nodes $\left._{K}\right), g_{\text {edges }}$ is one-to-one in edges ${ }_{L}-l_{\text {edgen }}($ edges $K)$, and all i_sourceg $(x)$ and $j$ larget $_{G}(x)$ with $x \in$ edges $_{G}-g_{e d g e s}\left(e d g e s_{L}\right)$ are in
has a natural pushout complement ( $K \stackrel{4}{\rightarrow} D \stackrel{b}{\rightarrow} G$ ). Moreover,

$$
\begin{aligned}
& \text { nodes }_{D}=\left(\text { nodes }_{G}-g_{\text {noden }}\left(\text { nodes }_{L}\right)\right) \cup g_{\text {nodes }\left(l_{\text {nodes } \left.\left(\text { nodes }_{K}\right)\right)}^{\text {edges }_{D}}=\left(\text { edges }_{G}-g_{\text {edges }}\left(\text { edges }_{L}\right)\right) \cup g_{\text {edges }}\left(l_{\text {edges }}\left(\text { edges }_{K}\right)\right),\right.}, \\
& \Omega_{0} \operatorname{reduct}(D)=\Omega_{0} \operatorname{reduct}(G)=\Omega_{0} \text {-ierms }
\end{aligned}
$$

$d$ is defined by $d_{\text {noded }}(x)=g_{\text {nedes }}\left(l_{\text {nedes }}(x)\right), d_{\text {edges }}(x)=g_{\text {edges }}\left(l_{\text {edges }}(x)\right)_{1} d_{\text {colours }}(x)=$ $g_{\text {coloura }}\left(l_{\text {colour, }}(x)\right.$ ), and $b$ consists of inclusions $b_{\text {nodes }}, b_{\text {edges }}$ and of the identity of colours.

A proof of this proposition for the graph part is essentially as the proof of a similar theorem for relational structures in [EKMRW 82]. For the colour part it follows from 2.3.

The category $\Omega_{\text {_graphs may be too large for some applications. For example, for }}$ logic programming the full subcategory of this category with graphs being jungles is more suitable, where a jungle is a (hyper)graph without cycles and without edges having a
common node in sources (ef. [CMREL 91] and [CRP 91]). For other applications we may need other subcategories in which pushouts and pushout complements, arbitrary or natural, may be different from those in $\Omega$ _graphs, or even may not exist. So, in the sequel we shall relate all our formalism to an arbitrary but fixed full subcategory $C$ of $\Omega$-graphs.

Productions representing rewriting rules for $\Omega$-graphs can be defined as follows.
By a production we mean any $p=(L \stackrel{\leftarrow}{\leftarrow} \dot{\rightarrow} R)$, where $L, K, R$ are $\Omega$-graphs in the subcategory $C$ with finite sets of nodes and edges and the $\Omega_{0}$-reducts coinciding with $\Omega_{0}$ terms, the $\Omega_{0}$-algebra of terms, and $l: K \rightarrow L, r: K \rightarrow R$ are $\Omega$-homomorphisms with $l_{\text {colours }}$ and $r_{\text {colour, }}$ being identities.

We call $K$ the gluing graph of $p$, and we call $L$ and $R$ the left side and the right side of $p$, respectively.

In order to be able to point to some elements of productions, we introduce suitable concepts of parametrized productions and parameters.

By a parametrized production we mean any $p=(L \stackrel{i}{\leftrightarrows} K \xrightarrow{\bullet} R, m, n)$, where $p r_{p}=$ ( $L \curvearrowleft K \stackrel{\emptyset}{\square}$ ) is a production and $m$ and $n$ are triples $m=\left(m_{\text {nodes }}, m_{\text {edges }}, m_{\text {colours }}\right)$ and $n=\left(n_{\text {nodes }}, n_{\text {edgees }}, n_{\text {colowrs }}\right)$ of partial mappings

$$
\begin{aligned}
& m_{\text {nodec }: \text { nodes }_{L} \supseteq \rightarrow \text { nodevariables }} \\
& m_{\text {edges }} \text { : edges } L \supseteq \rightarrow \text { edgevariables } \\
& m_{\text {colours }} \text { : colours }{ }_{L} \supseteq \rightarrow \text { colourvariables } \\
& n_{\text {nodes }} \text { : nodes } 2 \longrightarrow \text { nodevariables } \\
& n_{\text {edges }}: \text { edges }_{R} \supseteq \rightarrow \text { edgevariables } \\
& n_{\text {colourg }} \text { : colours }{ }_{R} \supseteq \rightarrow \text { colourvariables }
\end{aligned}
$$

such that

$$
\begin{aligned}
& m_{\text {nodes }}\left(l_{\text {nodeo }}(x)\right)=n_{\text {nodeo }}\left(r_{\text {nodeo }}(x)\right) \text { for all } x \in \text { nodes }_{K}, \\
& m_{\text {edges }}\left(l_{\text {edges }}(y)\right)=n_{\text {edgee: }}\left(r_{\text {edgeco }}(y)\right) \text { for all } y \in \operatorname{edgedes}_{K},
\end{aligned}
$$

and $m_{\text {eotoure, }} n_{\text {codour, }}$ are respectively an inclusion of a subset of colour-variables occurring in $\Omega_{0}$-terms assigned to edges of $L$ and an inclusion of a subset of colour-variables occurring in $\Omega_{0}$-terms assigned to edges of $R$.

Values of mappings $m_{\text {nodes }}, n_{\text {nodes }}, m_{\text {edger }} n_{\text {edgen }}, m_{\text {colouro }}, n_{\text {colour, }}$ are called respectively node-, edge-, and colour-parameters of $p$.
2.5. Example. In the case of the logic program in 1.1 atomic formulas corresponding to processes can be rewritten according to the parametrized productions in figures 2.1 2.4, where the labels play the role of parameters.

$\operatorname{sum}(Y, S) \Rightarrow \operatorname{sum}^{\prime}(Y, 0, S)$
Figure 2.1


$$
\operatorname{sum}^{\prime}([X \mid Y], P, S) \Rightarrow \operatorname{plus}(X, P, Q), \operatorname{sum}^{\prime}(Y, Q, S)
$$

Figure 2.2


Figure 2.3


$$
\operatorname{plus}(a, b, S) \Rightarrow S:=a+b
$$

Figure 2.4

Applications of usual productions to $\Omega$-graphs can be defined following the standard algebraic approach originated in [EPS 73]. An application of a parametrized production $p$ can be defined as an application of the usual production pr $_{p}$ in which all occurrences of each parameter are instantiated in the same way.

Let $A$ be a fixed $\Omega_{0}$-algebra, equipped possibly with some relations whose symbols belong to the language A .

By a rewriting step (or a direct derivation) over A via a parametrized production $p=(L \stackrel{I}{\leftarrow} \underset{\hookrightarrow}{\curvearrowleft}, m, n)$, we mean a pair $\sigma=(p, i)$ which consists of $p$ and of a diagram $i$ as in figure 2.5 in the subeategory $C$ of $\Omega$-graphs such that (1) and (2) for natural pushouts, the $\Omega_{0}$-reducts of $G, D, H$ coincide with $A, b_{\text {colour, }}$ and colour, are identities, and, for each sort $s$, we have:
$m_{s}(x)=m_{s}(y)$ implies $g_{0}(x)=g_{0}(y)$ whenever $m_{s}(x)$ and $m_{0}(y)$ are defined, $m_{0}(x)=n_{0}(y)$ implies $g_{0}(x)=h_{0}(y)$ whenever $m_{0}(x)$ and $n_{s}(y)$ are defined, $n_{s}(x)=n_{s}(y)$ implies $h_{s}(x)=h_{s}(y)$ whenever $n_{s}(x)$ and $n_{s}(y)$ are defined.

We say that $\sigma$ rewrites $G$ into $H$ and write it as $G \stackrel{\Rightarrow}{\Rightarrow} H$.


Figure 2.5
2.6. Example. The replacement of $s u m^{\prime}([1 \mid 2], 0, S)$ by plus $(1,0, P)$ and $s^{\prime}{ }^{\prime}([2], P, S)$ can be represented as a rewriting step as in figure 2.6.


$$
\operatorname{sum}^{\prime}([1 \mid 2], 0, S) \Rightarrow \text { plus }(1,0, P), \text { sum }^{\prime}([2], P, S)
$$

Figure 2.6

The concept of a direct derivation can be easily gereralized.
Given a set II of parametrized productions, by a derivation over $A$ via productions from $\Pi$ we mean a finite sequence $\sigma=\left(G_{0} \stackrel{5}{\rightrightarrows} G_{1} \stackrel{\theta}{\Rightarrow} \ldots \stackrel{y}{\Rightarrow} G_{i}\right)$ of rewriting steps over $A$ via productions from II. Given such a sequence $\sigma$, we say that it rewrites $G_{i}$ from $G_{0}$, write $G_{0} \stackrel{\leftrightarrows}{=} G_{i}$, and denote $G_{0}$ and $G_{i}$ by $\partial_{0}(\sigma)$ and $\partial_{1}(\sigma)$, respectively. By Derc,a, we denote the set of derivations of this kind with $G_{0}, G_{1}, \ldots, G_{i}$ having finite sets of nodes and edges.

Given a set $X \subseteq \operatorname{Der}_{\mathcal{A}} \wedge \boldsymbol{n}$ of derivations, by the relation of derivability via derivations from $X$ we mean the following relation $\operatorname{rel}(X)$ between graphs:

$$
(G, H) \in \operatorname{rel}(X) \text { iff } G=\partial_{0}(\sigma) \text { and } H=\partial_{1}(\sigma) \text { for some } \sigma \in X .
$$

## 3 Programs

We are interested in rewriting graphs according to some programs.
Intuitively, a program $p$ we have in mind is a description, possibly with some parameters, of an algorithm of rewriting graphs by applying productions. In particular, it describes how a given graph $G$ and a given, possibly partial, valuation $v$ of variables in this graph, which is defined for parameters of $p$, are transformed into subsequent graphs and valuations of variables until reaching a final result.

In order to facilitate a sort of busy waiting of processes as mentioned in section 1, we admit a recursion such that programs may call themselves without executing any real action (an unguarded recursion). Theoretically it leads to infinite idle loops, but in practice such loops do not happen due to a sort of fairness which is usually ensured.

Programs are defined presupposing a set programidentifiers of program identifiers, each identifier with an arity which specifies a number of node-, edge-, and colourparameters. They are given by program expressions $p, q, r, \ldots$ which are of the following kinds:
(1) A constant nil. This program expression represents doing nothing.
(2) A parametrized production $p$. This program expression represents a possible rewriting step $\sigma=(p, i)$ as in figure 2.5 which transforms a graph $G$ and a valuation $v$ of parameters of $p$ in $G$ into a graph $H$ and a valuation $w$ of parameters of $p$ in $H$, where $v_{0}\left(m_{0}(x)\right)=g_{0}(x)$ and $w_{s}\left(n_{0}(y)\right)=h_{0}(y)$ for each sort $s$ and all $x, y$ of this sort.
(3) A result py of a substitution $\gamma$ of new variables for parameters in a program expression $p$. This program expression represents an activity which transforms a graph $G$ and a valuation $v$ of parameters of $p \gamma$ in the way in which the activity represented by $p$ transforms $G$ and the valuation $\gamma \circ v$, i.e. the superposition of $\gamma$ and $v$.
(4) A conditional if a then $p$ else $q$, where $\alpha$ is a formula in the language $\Lambda$ and $p, q$ are program expressions. This program expression represents the choice and execution of $p$ or $q$ depending on the satisfaction of $\alpha$ for the given graph $G$ and the given valuation $v$ of free variables of $\alpha$ and parameters of $p$ and $q$.
(5) A sequential composition $p ; q$ of program expressions $p$ and $q$. This program expression represents an execution of $p$ followed by an execution of $q$.
(6) A parallel composition $p \| q$ of program expressions $p$ and $q$. This program expression represents a parallel execution of $p$ and $q$ which can be viewed as an arbitrary interleaving of actions of $p$ and $q$.
(7) An indeterministic sum $p+q$ of program expressions $p$ and $q$. This program expression represents an indeterministic choice and execution of $p$ or $q$.
(8) An indeterministic sum $\Sigma x p$, where $x$ is a variable and $p$ is a program expression. This program expression represents an activity which transforms a graph $G$ and a valuation $v$ of parameters of $p$ in $G$ in the way in which the activity represented by $p$ transforms $G$ and a valuation $v^{\prime}$ obtained from $v$ by an indeterministic choice of a suitable value of $x$. If there is no such a value for $x$ then the represented activity reduces to doing nothing.
(9) A defined program expression

$$
\varphi_{k}\left(y_{k 1}, y_{k 2}, \ldots\right) \text { where }\left(\varphi_{1}\left(y_{11}, y_{12}, \ldots\right)=\psi_{1}, \ldots, \varphi_{n}\left(y_{n 1}, y_{n 2}, \ldots\right)=\psi_{n}\right)
$$

where $\varphi_{1}, \ldots, \varphi_{n}$ are program identifiers and $y_{11}, y_{12}, \ldots, y_{n 1}, y_{n 2}, \ldots$ are parameters as specified by the respective arities and each $\psi_{i}$ is a program expression which may contain expressions of the form $\varphi_{1}\left(z_{i 11}, z_{i 12}, \ldots\right), \ldots, \varphi_{n}\left(z_{i n 1}, z_{i n 2}, \ldots\right)$ and is such that all $z_{i 11}, z_{i 12}, \ldots, z_{i n 1}, z_{i n 2}, \ldots$ and other parameters of $\psi_{i}$ occur among $y_{i 1}, y_{i 2}, \ldots$. This program expression represents an activity whose execution for $y_{k 1}, y_{k 2}, \ldots$ is defined by $\psi_{k}$. As in $\psi_{k}$ there may occur $\psi_{1}\left(z_{k 11}, z_{k 12}, \ldots\right), \ldots \varphi_{n}\left(z_{k n 1}, z_{k n 2}, \ldots\right)$, one has to define the respective activities by the equations $\varphi_{1}\left(y_{11}, y_{12}, \ldots\right)=\psi_{1}, \ldots, \nu_{n}\left(y_{n 1}, y_{n 2}, \ldots\right)=$ $\psi_{n}$, and consider an occurrence of $\varphi_{j}\left(z_{i j 1}, z_{i j 2}, \ldots\right)$ in $\psi_{i}$ as a call of the respective $\psi_{j}$. In particular, each program expression of the form
$\varphi$ where ( $\varphi=$ if $\alpha$ then $p ; \varphi$ else nil)
is equivalent to the standard iteration construct while $\alpha$ do $p$.
(10) An atomic program expression atom $p$, where $p$ is a program expression. This program expression represents the activity of successfully executing $p$ as one indivisible step.

Thus we have the following syntax of program expressions:

```
p::= nil
    | < parametrized production >
    |p\gamma
    |if \alpha then p elseq
    |p;q
    |p|q
    |p+q
    |\Sigmaxp
    |\mp@subsup{\varphi}{k}{}(\mp@subsup{y}{k1}{},\mp@subsup{y}{k2}{},\ldots) where ( }\mp@subsup{p}{1}{}=\mp@subsup{\psi}{1}{},\ldots,\mp@subsup{\varphi}{n}{}=\mp@subsup{\psi}{n}{}
    |atom p
```

To each program expression $p$ there correspond a set $F P(p)$ of node-, edge-, and colour-variables called free parameters of $p$, which can be defined as follows:
(1) If $p$ is a parametrized production then $F P(p)$ is the set of parameters of $p$.
(2) $F P($ nil $)=0$.
(3) $F P(p \gamma)=\gamma(F P(p))$.
(4) $F P($ if $\alpha$ then $p$ else $q)$ is the union of $F P(p) \cup F P(q)$ and the set of free variables of $\alpha$.
(5) $F P(p ; q)=F P(p \| q)=F P(p+q)=F P(p) \cup F P(q)$.
(6) $F P(\Sigma x p)=F P(p)-\{x\}$.
(7) $F P\left(\varphi_{k}\left(y_{k 1}, y_{k 2}, \ldots\right)\right.$ where $\left.\left(\varphi_{1}=\psi_{1}, \ldots, \varphi_{n}=\psi_{n}\right)\right)=\left\{y_{k 1}, y_{k 2}, \ldots\right\}$.
(8) $F P(\operatorname{atom} p)=F P(p)$.
3.1. Example. A program of computing the sum of elements of a list of integers as in 1.1 can be defined as follows:


The instructions of replacement which occur in this program are parametrized productions as in 2.5. Formulas occurring in the program are abbreviations of formulas of the first order language $\Lambda$. For instance, the formula $\xi$ represents $[X \mid Y]$ is an abbreviation of a formula which states the existence of an edge with the colour |, the source node $\xi$, and the target nodes $X$ and $Y$.

## 4 Semantics

The way in which pairs consisting of graphs and valuations of variables in these graphs are transformed by executing programs can be described in the form of a labelled transition system which consists of a universe conf of configurations and a transition relation $\rightarrow$. When considered together with suitable fairness assumptions, such a system allows to definc all practically possible program computations.

The universe conf consists of configurations of the form $c=(p, G, v)$, where $p$ is a program expression, $G$ is a graph, and $v$ is a (possibly partial) valuation of variables in $G$ such that the defined values of node-, edge-, and colour variables arc respectively nodes, edges, and colours of $G$.

The transition relation $\rightarrow$ consists of transitions of the form $t=\left(c, a, c^{\prime}\right)$, where $c, c^{\prime}$ are configurations and $a$ is either an invisible action $r$ which docs not change the
configuration (that is such that $c=c^{\prime}$ ) or an action of applying a production or exceuting an atomic program. Denoting by actions the set of possible actions we can define this relation as the smallest $\rightarrow \subseteq$ con $f \times$ actions $\times$ con $f$ satisfying the following conditions:
(1) $(p, G, v) \xrightarrow{円}($ nil $, H, w)$ for each parametrized production $p$ and $G, H, v, w$ such that there is a rewriting step $\sigma=(p, i)$ with the diagram $i$ as in figure 2.5 and $g_{0}(x)=$ $v\left(m_{0}(x)\right), h_{0}(y)=w\left(m_{0}(y)\right.$ for each sort $s$ and all $x, y$ such that $m_{0}(x)$ and $n_{0}(y)$ are defined.
(2) (atom $p, G, v) \xrightarrow{\text { atom } p}\left(n i l, G^{\prime}, v^{\prime}\right)$ for each program $p$ and $G, G^{\prime}, v, v^{\prime}$ such that there exists a finite sequence of transitions of the form

$$
(p, G, v) \stackrel{a_{4}}{\rightarrow} \ldots\left(\mathrm{nil}, G^{\prime}, v^{\prime}\right)
$$

(3) If $(p, G, \gamma \circ v) \stackrel{\circ}{\rightarrow}\left(p^{\prime}, G^{\prime}, \gamma \circ v^{\prime}\right)$ then $(p \gamma, G, v) \stackrel{\circ}{\rightarrow}\left(p^{\prime} \gamma, G^{\prime}, v^{\prime}\right)$.
(4) If $(p, G, v) \xrightarrow{a}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ and the formula $f$ is satisfied for the valuation $v$ then (if $f$ then $p$ else $q, G, v) \xrightarrow{\circ}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$.
(5) If $(q, G, v) \stackrel{\circ}{\rightarrow}\left(q^{\prime}, G^{\prime}, v^{\prime}\right)$ and the formula $f$ is not satisficd for the valuation $v$ then (if $f$ then $p$ else $q, G, v) \xrightarrow{o}\left(q^{\prime}, G^{\prime}, v^{\prime}\right)$.
(6) If $(p, G, v) \xrightarrow{\circ}\left(n i l, G^{\prime}, v^{\prime}\right)$ then $(p ; q, G, v) \xrightarrow{o}\left(q, G^{\prime}, v^{\prime}\right)$.
(7) If $(p, G, v) \xrightarrow{a}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ then $(p ; q, G, v) \xrightarrow{a}\left(p ; q, G^{\prime}, v^{\prime}\right)$.
(8) If $(p, G, v) \xrightarrow{a}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ then $(p \| q, G, v) \xrightarrow{\circ}\left(p^{\prime} \| q, G^{\prime}, v^{\prime}\right)$.
(9) If $(q, G, v) \xrightarrow{\circ}\left(q^{\prime}, G^{\prime}, v^{\prime}\right)$ then $(p \| q, G, v) \xrightarrow{\circ}\left(p \| q^{\prime}, G^{\prime}, v^{\prime}\right)$.
(10) If $(p, G, v) \xrightarrow{\circ}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ then $(p+q, G, v) \stackrel{a}{\rightarrow}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$.
(11) If $(q, G, v) \xrightarrow{\infty}\left(q^{\prime}, G^{\prime}, v^{\prime}\right)$ then $(p+q, G, v) \xrightarrow{a}\left(q^{\prime}, G^{\prime}, v^{\prime}\right)$
(12) ( $\Sigma x p, G, v) \xrightarrow{G}($ nil $, G, v)$ for each program expression $p$ and all $G, v$ such that $v(x)$ is not defined.
(13) If $(p, G, v) \xrightarrow{a}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ for some $v$ such that $v(x)$ is defined then $(\Sigma x p, G, w) \xrightarrow{\bullet}$ $\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ for $w=v-\{(x, v(x))\}$.
(14)

$$
\begin{aligned}
& \left(\varphi_{k}\left(y_{k 1}, y_{k 2}, \ldots\right) \text { where }\left(\varphi_{1}=\psi_{1}, \ldots, \varphi_{n}=\psi_{n}\right), G, v\right) \xrightarrow{r} \\
& \left(\varphi_{j}\left(y_{j 1}, y_{j 2}, \ldots\right) \text { where }\left(\varphi_{1}=\psi_{1}, \ldots, \varphi_{n}=\psi_{n}\right), G, v\right)
\end{aligned}
$$

whenever $\varphi_{j}\left(y_{j 1}, y_{j 2}, \ldots\right)$ is the first program expression in $\psi_{k}^{\prime}$ which is obtained by substituting in $\dot{\phi}_{k}$ the program expression

$$
\psi_{i}\left(y_{11}, y_{12}, \ldots\right) \text { where }\left(\varphi_{1}=\psi_{1}, \ldots, \varphi_{n}=\psi_{n}\right)
$$

for each occurrence of $\varphi_{i}\left(y_{i 1}, y_{i 2}, \ldots\right)$.
(15) If $\left(\psi_{k}^{\prime}, G, v\right) \xrightarrow{a}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)$ for $\psi_{k}^{\prime}$ obtained by substituting in $\psi_{k}$ the program expression

$$
\varphi_{i}\left(y_{1}, y_{i 2}, \ldots\right) \text { where }\left(\nu_{1}=\psi_{1}, \ldots, \psi_{n}=\psi_{n}\right)
$$

for each occurrence of $\varphi_{i}\left(y_{i 1}, y_{i z}, \ldots\right)$, then

$$
\left(\varphi_{k}\left(y_{k 1}, y_{k 2}, \ldots\right) \text { where }\left(\varphi_{1}=\psi_{1}, \ldots, \varphi_{n}=\psi_{n}\right), G, v\right) \stackrel{o}{\rightarrow}\left(p^{\prime}, G^{\prime}, v^{\prime}\right)
$$

The transition relation allows to define computations of programs and the respective relations between data and results.

Formally, a computation of a program $p$ is defined as a sequence of transitions of the form

$$
u=\left((p, G, v) \stackrel{\circ}{\rightarrow}\left(p_{1}, G_{1}, v_{1}\right) \stackrel{\text { q... }}{\rightarrow}\right)
$$

Where $u$ is either countably infinite or it has a terminal configuration of the form (nil, $G^{\prime}, v^{\prime}$ ). The pairs $(G, v)$ and $\left(G^{\prime}, v^{\prime}\right)$ (if $u$ terminates) are called respectively the data and the resull of $u$.

In reality it is usually ensured that only such computations are possible which enjoy a fairness property. Consequently, in the sequel by a computation of a program $p$ we shall mean only such a computation $u$ of $p$ which is fair in the sense that there is no transition of $p$ which is permanently possible starting from a configuration $c$ of $u$ and does not occur among the transitions of $u$ which follow $c$.

The resulting relation of a program $p, \operatorname{res}(p)$, is defined as the relation which holds between the data and the results of finite computations of $p:(G, v) r e s(p)\left(G^{\prime}, v^{\prime}\right)$ iff there exists a computation of $p$ of the form: $(p, G, v) \xrightarrow{\circ} \ldots \stackrel{9}{\rightarrow}$ ( $\left.\mathrm{pil}, G^{\prime}, v^{\prime}\right)$.

## 5 Resulting relations of programs

The possibility of using computations of programs to define the respective resulting relations suggests that an input-output semantics could be defined directly in terms of resulting relations. Unfortunately, such a definition is impossible because of the lack of compositionality of the correspondence between programs and their resulting relations. There are two sources of this situation. One of them is the parallel composition, where the resulting relation of a program obtained by composing given programs depends not only on the resulting relations of these programs, but also on the resulting relations of smaller program components. For example, for a program $p \| q$, where $p=p_{1} ; p_{2}, q=q_{1} ; q_{2}$, and $p_{1}, p_{2}, q_{1}, q_{3}$ are parametrized productions the resulting relation is

$$
\begin{gathered}
\operatorname{res}(p \| q)=\operatorname{res}\left(p_{1} ; p_{2} ; q_{1} ; q_{2}\right) \cup \operatorname{res}\left(p_{1} ; q_{1} ; p_{2} ; q_{2}\right) \cup \operatorname{res}\left(p_{1} ; q_{1} ; q_{2} ; p_{2}\right) \\
\cup \operatorname{res}\left(q_{1} ; p_{1} ; p_{2} ; q_{2}\right) \cup \operatorname{res}\left(q_{1} ; p_{1} ; q_{2} ; p_{2}\right) \cup \operatorname{res}\left(q_{1} ; q_{2} ; p_{1} ; p_{2}\right)
\end{gathered}
$$

and it cannot be expressed in terms of $\operatorname{res}(p)=\operatorname{res}\left(p_{1} ; p_{2}\right)$ and $\operatorname{res}(q)=\operatorname{res}\left(q_{1} ; q_{2}\right)$. Another source of the mentioned situation is recursion, where the resulting relation of a program defined by a mutual recursion need not be definable by the corresponding system of equations in the algebra of relations. For example, for the program $p=X$ where ( $X=$
nil; $X$ ), each finite graph $G$, the resulting relation is identity and it is different from the least relation $R$ satisfying $R=$ identity $\circ R$ since such the latter is the empty relation $B$.

The lack of compositionality w. r. to the parallel composition and recursion shows that there is no chance for a direct input-output semantics of the considered programs. In particular, an operational semantics as presented cannot be avoided even if we are interested only in the resulting relations of programs. On the contrary, in the situation in which such relations cannot be derived from programs directly, a semantics of this kind becomes an important tool of defining the resulting relations.

The reasonning about resulting relations of programs can be supported by a number of properties of such relations.
5.1. Proposition. The following properties hold true for the resulting relations of programs:
(1) res(skip) $=$ identity .
(2) If $p$ is a parametrized production then $(G, v) r e s(p)(H, w)$ if there is a rewriting step $\sigma=(p, i)$ with the diagrami as in figure 2.5 and $g_{0}(x)=v\left(m_{0}(x)\right), h_{0}(y)=v\left(m_{0}(y)\right.$ for each sort $s$ and all $x, y$ such that $m_{s}(x)$ and $n_{0}(y)$ are defined.
(3) $(G, v)$ res $(p \gamma)\left(G^{\prime}, v^{\prime}\right)$ iff $(G, \gamma \circ v)$ res $(p)\left(G^{\prime}, \gamma \circ v^{\prime}\right)$.
(4) $(G, v)$ res(if $f$ then $p$ else $q)\left(G^{\prime}, v^{\prime}\right)$ iff either $f$ is satisfied for $G$ and $v$ and $(G, v)$ res $(p)\left(G^{\prime}, v^{\prime}\right)$ or $f$ is not satisfied and $(G, v)$ res $(q)\left(G^{\prime}, v^{\prime}\right)$.
$(5) \operatorname{res}(p ; q)=\operatorname{res}(p) \circ \operatorname{res}(q)$.
(6) $\operatorname{res}(p+q)=\operatorname{res}(p) \cup \operatorname{res}(q)$.
(7) $\operatorname{res}(\Sigma x p)=U(\operatorname{res}(p): i \in I)$, where $I$ is the set of possible values of valuations for x.

A proof is of this proposition is straightforward.
The class of resulting relations of programs is rich enough to represent the usual derivability relation.

Taking into account the definition of the resulting relation of a program and the definition of the semantics of programs, we obtain the following realization of the relation of derivability.
5.2. Proposition. Let $\Pi=\left\{p_{1}, \ldots, p_{m}\right\}$ be a finite set of parametrized productions. There is a program $p$ such that $H$ is derivable from $G$ via productions from $\Pi$ iff $(G, v)$ res $(p)\left(H, v^{\prime}\right)$ for some $v$ and $v^{\prime}$. In particular, we may define such a program as

$$
p=X \text { where }(X=q ; X+\text { nil })
$$

where

$$
q=\left(\Sigma x_{1}\right) \ldots\left(\Sigma x_{m}\right)\left(p_{1}+\ldots+p_{m}\right)
$$

and $\left\{x_{1}, \ldots, x_{m}\right\}$ is the set of parameters of productions $p_{1}, \ldots, p_{m}$.

## 6 Recapitulation

We have presented conceptual means for programming concurrent processes of rewriting graphs by applying productions. These means are flexible enough to cover the usual rewriting. However, their possibilities go much beyond such particular cases due to the powerful mechanisms of parameters, recursion, concurrency, and operating on colours.

The presented formalism is brought to the form of (a kernel of) a programming language with a precise syntax and semantics.

The semantics defines computations of each program $p$. These computations represent the possible ways of transforming a given graph $G$ and a given valuation of variables in this graph, and thus they determine a resulting relation res $(p)$ of $p$. The possibility of determining such a relation is important since there is no simpler way of computing it directly from the program.

The semantics presented in the paper represents concurrency as an arbitrary interleaving of actions. Nevertheless, it contains implicitly all the information about the existing concurrency. Moreover, there seems to be a chance of refining it to a form in which concurrency would be reflected in a more explicit way as in [MR 92]. How to do it is however a problem which we leave open in the present paper.

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